

Lightcuts

Jan Kautz, 2009-2010

Lightcuts

- Efficient, accurate complex illumination



Environment map lighting & indirect Time 111s
Textured area lights & indirect Time 98s

(640x480, Anti-aliased, Glossy materials)

Scalable

- Scalable solution for many point lights
 - Thousands to millions
 - Sub-linear cost

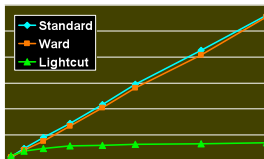


Tableau Scene

Complex Lighting

- Simulate complex illumination using point lights
 - Area lights
 - HDR environment maps
 - Sun & sky light
 - Indirect illumination
- Unifies illumination
 - Enables tradeoffs between components

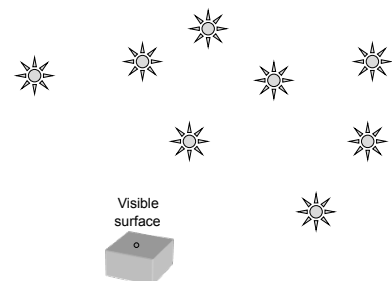


Area lights + Sun/sky + Indirect

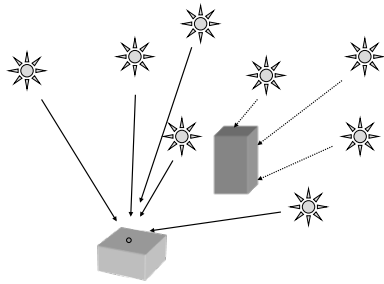
Overview

- Problem
- Pre-Process
 - Convert Illumination to Point Lights
 - Tree Building
- Run-Time
 - Cut

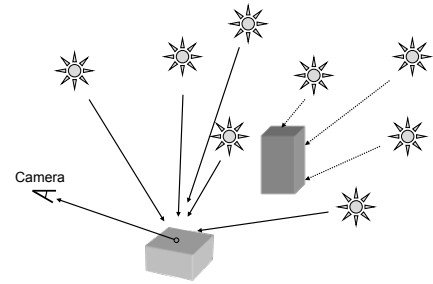
Lightcuts Problem



Lightcuts Problem

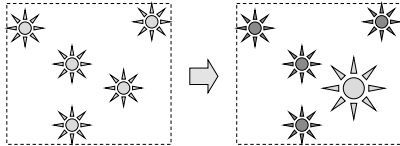


Lightcuts Problem



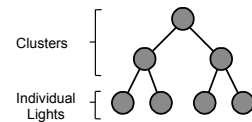
Key Concepts

- Light Cluster
 - Approximate many lights by a single brighter light (the representative light)



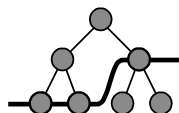
Key Concepts

- Light Cluster
 - Approximate many lights by a single brighter light (the representative light)
- Light Tree
 - Binary tree of lights and clusters

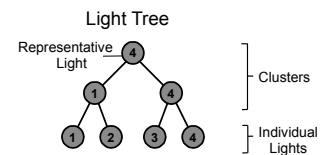
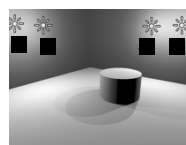


Key Concepts

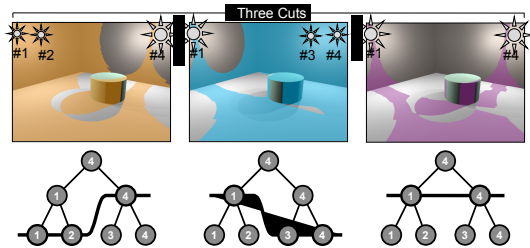
- Light Cluster
- Light Tree
- A Cut
 - A set of nodes that partitions the lights into clusters



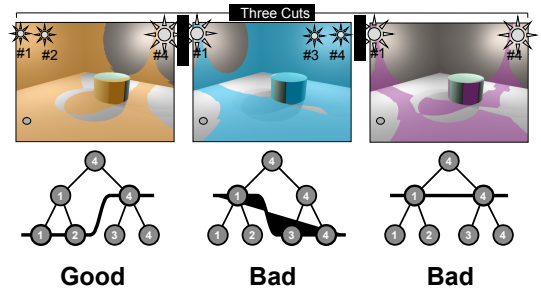
Simple Example



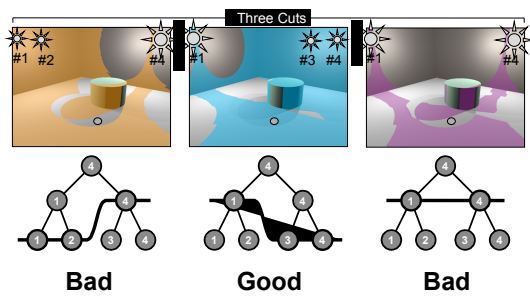
Three Example Cuts



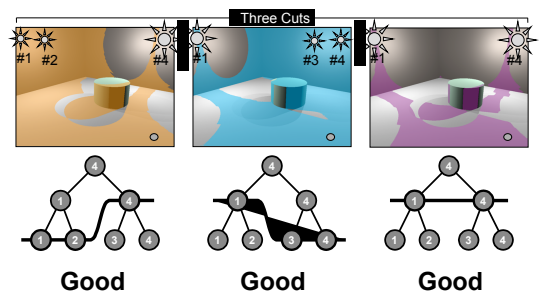
Three Example Cuts



Three Example Cuts



Three Example Cuts



Algorithm Overview

- Pre-process
 - Convert illumination to point lights
 - Build light tree
- For each eye ray
 - Choose a cut to approximate the illumination

Convert Illumination

- HDR environment map
 - Apply captured light to scene
 - Convert to directional point lights using [Agarwal et al. 2003]
- Indirect Illumination
 - Convert indirect to direct illumination using Instant Radiosity [Keller 97]
 - Caveats: no caustics, clamping, etc.
 - More lights = more indirect detail



Algorithm Overview

- Pre-process
 - Convert illumination to point lights
 - Build light tree
- For each eye ray
 - Choose a cut to approximate the local illumination
 - Cost vs. accuracy
 - Avoid visible transition artifacts

Perceptual Metric

- Weber's Law
 - Contrast visibility threshold is fixed percentage of signal
 - Used 2% in our results
- Ensure each cluster's error < visibility threshold
 - Transitions will not be visible
 - Used to select cut

Illumination Equation

$$\text{result} = \sum_{\text{lights}} M_i G_i V_i I_i$$

M_i | G_i | V_i | I_i
 Material term | Geometric term | Visibility term | Light intensity

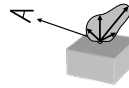
More formal:

$$L(x, \omega_r) = [L_e(x, \omega_r)] + \sum_i f_r(\omega_r, \omega_i) \omega_i \cdot n \frac{1}{\|y_i - x\|^2} V(x, \omega_i) I(y_i)$$

Illumination Equation

$$\text{result} = \sum_{\text{lights}} M_i G_i V_i I_i$$

M_i | G_i | V_i | I_i
 Material term | Geometric term | Visibility term | Light intensity

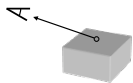


Material term is the BRDF: $f_r(\omega_r, \omega_i) \omega_i \cdot n$

Illumination Equation

$$\text{result} = \sum_{\text{lights}} M_i G_i V_i I_i$$

M_i | G_i | V_i | I_i
 Material term | Geometric term | Visibility term | Light intensity

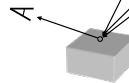


Geometric term is (for point lights): $\frac{1}{\|y_i - x\|^2}$

Illumination Equation

$$\text{result} = \sum_{\text{lights}} M_i G_i V_i I_i$$

M_i | G_i | V_i | I_i
 Material term | Geometric term | Visibility term | Light intensity

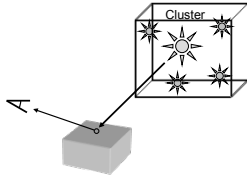


Visibility is defined as: $V(x, \omega_i) = \begin{cases} 1 \\ 0 \end{cases}$

Cluster Approximation

$$\text{result} \approx M_j G_j V_j \sum_{\text{lights}} I_i$$

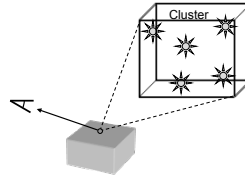
j is the representative light



Cluster Error Bound

$$\text{error} \leq M_{ub} G_{ub} V_{ub} \sum_{\text{lights}} I_i$$

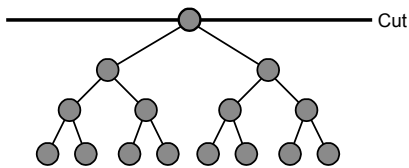
- Bound each term
 - Visibility ≤ 1 (trivial)
 - Intensity is known
 - Bound material and geometric terms using cluster bounding volume



ub == upper bound

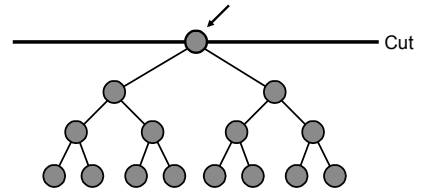
Cut Selection Algorithm

- Start with coarse cut (eg, root node)



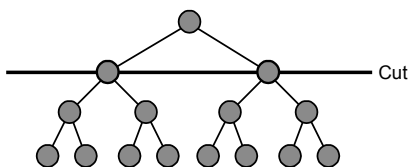
Cut Selection Algorithm

- Select cluster with largest error bound

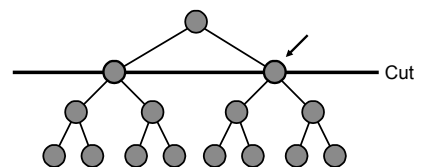


Cut Selection Algorithm

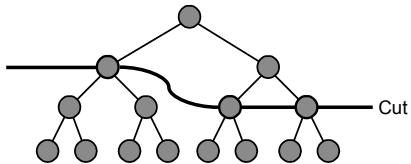
- Refine if error bound $> 2\%$ of total



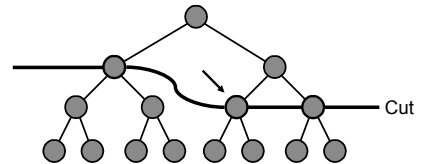
Cut Selection Algorithm



Cut Selection Algorithm

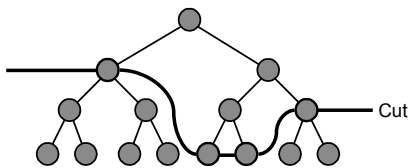


Cut Selection Algorithm



Cut Selection Algorithm

- Repeat until cut obeys 2% threshold



Kitchen, 388K polygons, 4608 lights (72 area sources)



Combined Illumination



Lightcuts 128s
4 608 Lights
(Area lights only)

Lightcuts 290s
59 672 Lights
(Area + Sun/sky + Indirect)

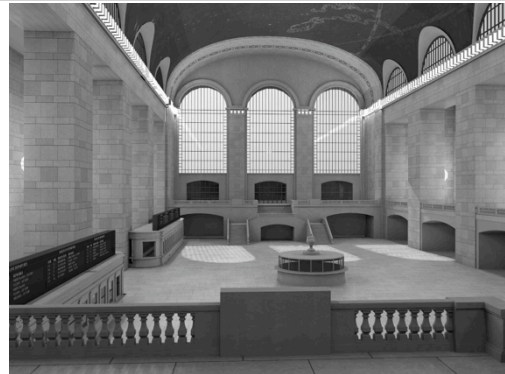
Combined Illumination



Lightcuts 128s
4 608 Lights
(Area lights only)
Avg. 259 shadow rays / pixel



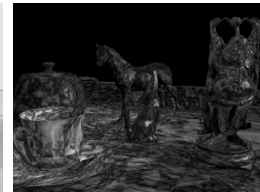
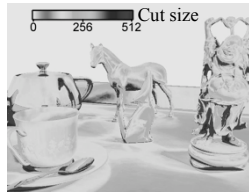
Lightcuts 290s
59 672 Lights
(Area + Sun/sky + Indirect)
Avg. 478 shadow rays / pixel
(only 54 to area lights)



Grand Central, 1.46M polygons, 143464 lights, (Area+Sun/sky+Indirect)
Avg. shadow rays per eye ray 46 (0.03%)



Tableau, 630K polygons, 13 000 lights, (EnvMap+Indirect)
Avg. shadow rays per eye ray 17 (0.13%)



Cut size
0 256 512

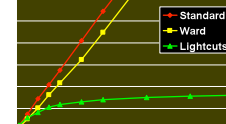
Scalable

- Scalable solution for many point lights
 - Thousands to millions
 - Sub-linear cost

Tableau Scene



Kitchen Scene



Bigscreen, 628K polygons, 639528 lights, (Area+Indirect)
Avg. shadow rays per eye ray 17 (0.003%)

Summary

- Unified illumination handling
- Scalable solution for many lights
 - Locally adaptive representation (the cut)
- Analytic cluster error bounds
 - Most important lights always sampled
- Perceptual visibility metric

The End

