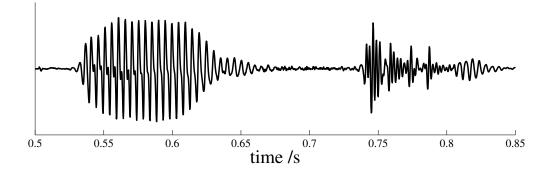
# A new generative model for sounds: The Gaussian Modulation Cascade Process

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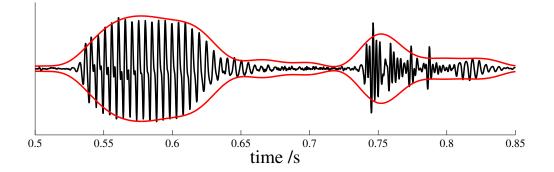
Maneesh Sahani (maneesh@gatsby.ucl.ac.uk)

Gatsby Computational Neuroscience Unit, 09/12/2006

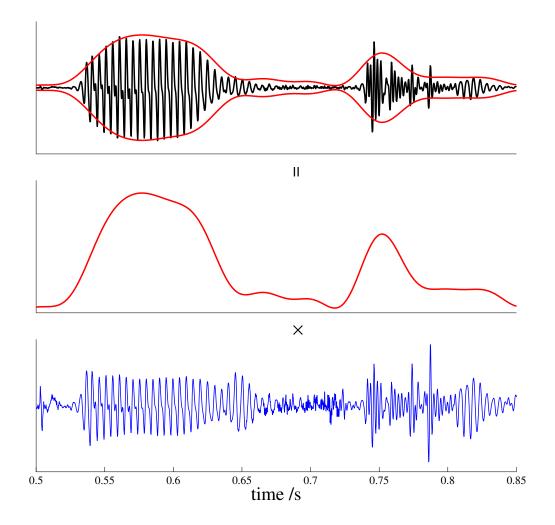
# Motivation



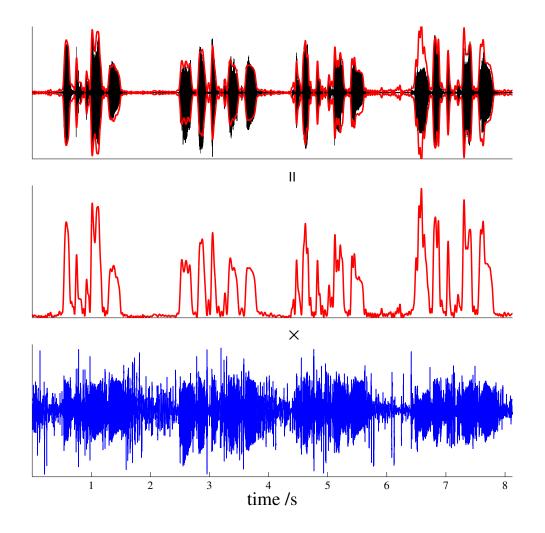
# Motivation



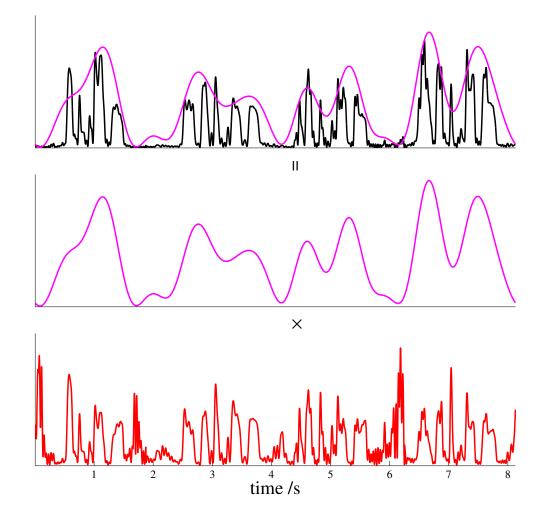
# **Motivation: Traditional AM**



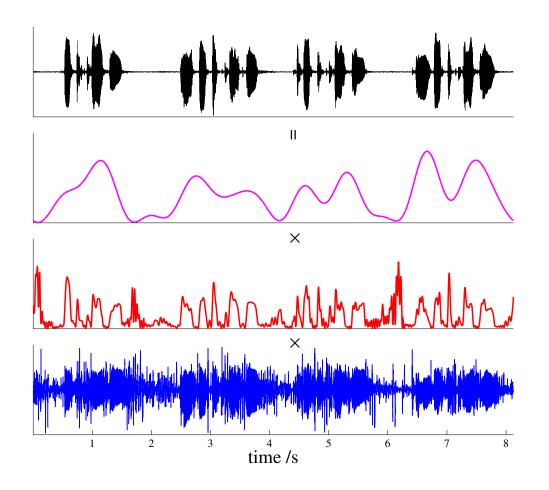
# **Motivation: Traditional AM**



# Motivation: Demodulate the Modulator

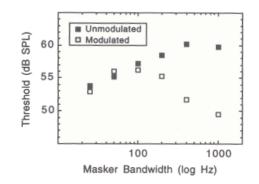


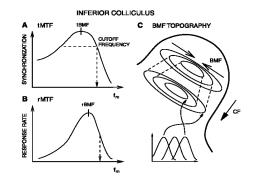
## **Motivation: Demodulation Cascade**



# AM: a candidate organising principle in the Auditory System?

- The auditory system listens attentively to Amplitude Modulation
- Examples include Comodulation Masking Release in psychophysics, and a possible topographic mapping of AM in the IC from electrophysiology.
- Main goal: discover computational principles underpinning auditory processing.
- But armed with a generative model you can do: sound denoising, source segregation, fill in missing data/remove artifacts etc.





Model	latents			learnable
	sparse	share power	slowly varying	
ICA	$\checkmark$	×	×	$\checkmark$
SC	$\checkmark$	×	×	$\checkmark$

Assumption: Latent variables are sparse.

Model	latents			learnable
	sparse	share power	slowly varying	lealnable
ICA		×	×	
SC	$\checkmark$	×	×	$\checkmark$
GSM	$\checkmark$	$\checkmark$	×	$\checkmark$

Assumption: Latents are sparse, and share power.

- $\mathbf{x} = \lambda \mathbf{u}$ 
  - $\lambda \geq 0$  a positive scalar random variable,  $\mathbf{u} \sim G(0,Q)$

Model	latents			learnable
	sparse	share power	slowly varying	leanable
ICA		×	×	$\checkmark$
SC		×	×	$\checkmark$
GSM		$\checkmark$	×	
SFA	×	×	$\checkmark$	$\checkmark$

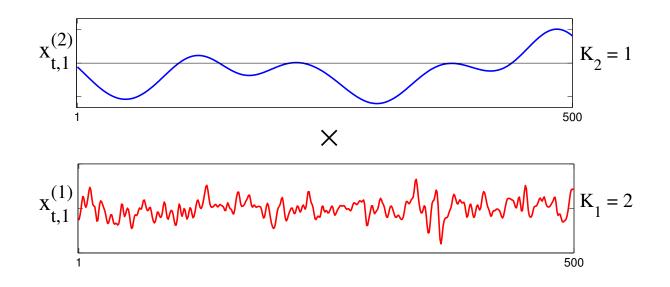
Assumption: Latents are slow.

Model	latents			learnable
	sparse	share power	slowly varying	leanable
ICA		×	×	$\checkmark$
SC	$\checkmark$	×	×	$\checkmark$
GSM	$\checkmark$	$\checkmark$	×	$\checkmark$
SFA	×	×	$\checkmark$	$\checkmark$
Bubbles	$\checkmark$	$\checkmark$	$\checkmark$	×

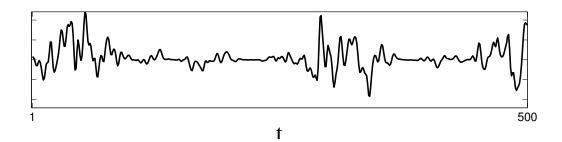
Assumption: Latents are sparse, slow (and share power).

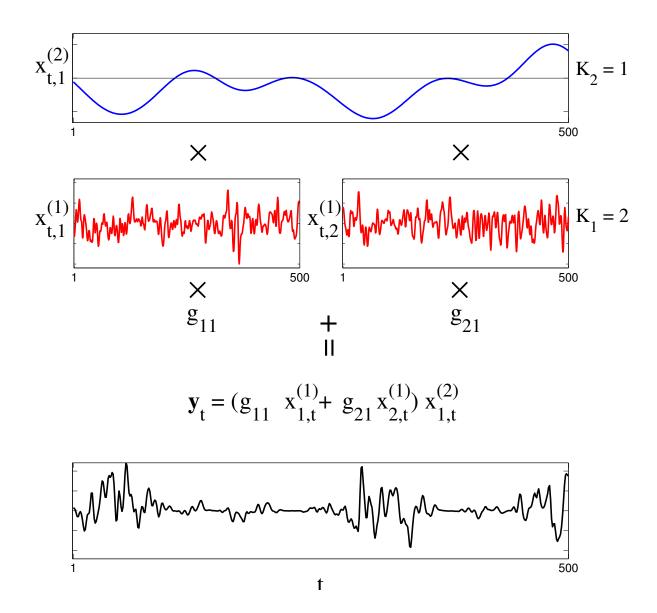
## Desirable features of a new generative model

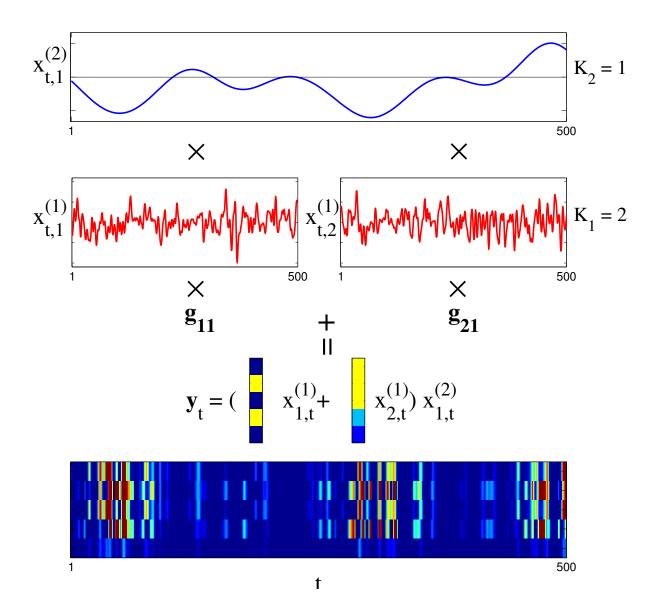
- 1. Sparse outputs.
- 2. Explicit temporal dimension, smooth latent variables.
- 3. Hierarchical prior that captures the AM statistics of sounds at different time scales: cascade of modulatory processes, with slowly varying processes at the top modulating more rapidly varying signals towards the bottom.
- 4. Learnable; and we would like to preserve information about the uncertainty, and possibly correlations, in our inferences.

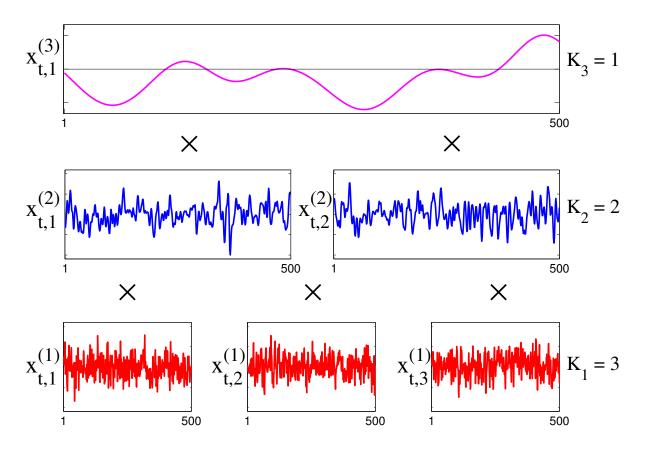


 $|| y_t = x_{1,t}^{(1)} x_{1,t}^{(2)}$ 



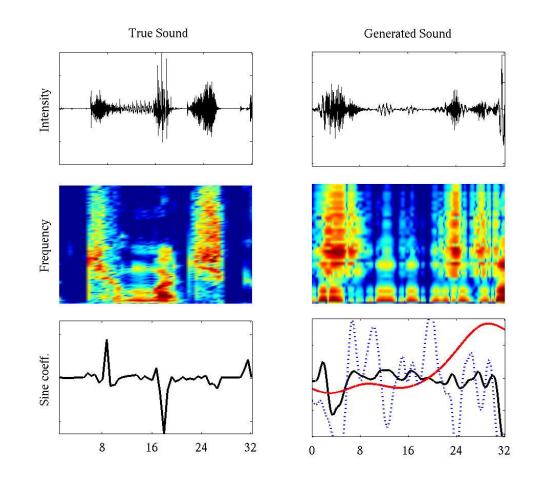






 $\mathbf{y}_{t} = \mathbf{x}_{t,1}^{(3)} \left[ \begin{array}{ccc} \mathbf{x}_{t,1}^{(2)} & (\mathbf{x}_{t,1}^{(1)} & \mathbf{g}_{111} + \mathbf{x}_{t,2}^{(1)} & \mathbf{g}_{211} + \mathbf{x}_{t,3}^{(1)} & \mathbf{g}_{311} \right] + \mathbf{x}_{t,2}^{(2)} & (\mathbf{x}_{t,1}^{(1)} & \mathbf{g}_{121} + \mathbf{x}_{t,2}^{(1)} & \mathbf{g}_{221} + \mathbf{x}_{t,3}^{(1)} & \mathbf{g}_{321} \right] \right]$ 

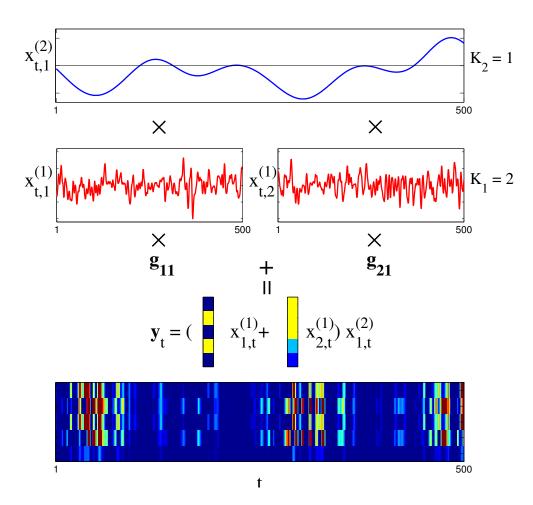
$$M = 4, K_1 = 4, K_2 = 2, K_3 = 2, K_4 = 1, D = 80$$



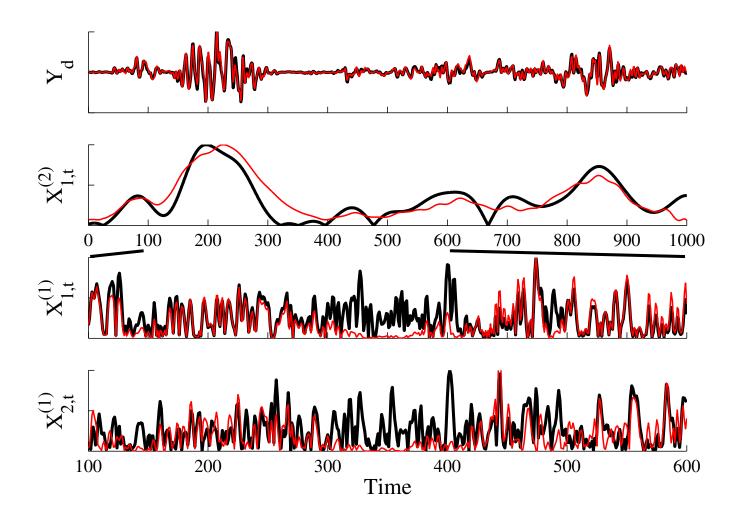
# Inference and learning

- Inference and learning by EM has an **intractable E-Step**.
- But due to the structure of the non-linearity variational EM can be used.
- Key point: If we freeze all the latent time-series bar one, the distribution over the unfrozen chain is Gaussian.
- Leads to a family of efficient variational approximations:  $p(X|Y) \approx \prod_m q(X_{1:T,1:K_m}^{(m)})$ , where each approximating distribution is a Gaussian.

## **Inference and Learning: Proof of concept**



#### **Inference and Learning: Proof of concept**



# **Current work and Future directions**

- Apply to **natural sounds** (require good initialisation)
- Generalise the model to have
  - non-local features: to capture sweeps
  - correlations in the prior: to capture the mutual-exclusivity of voiced and unvoiced sections of speech
- **Representation**: real sounds live on a hyper-plane in STFT space: can we project our model onto this manifold?
- How do we map posteriors to spike-trains:  $p(\text{spike trains } | \mathbf{y}) = f[Q(\mathbf{x} | \mathbf{y})]$ ?

Extra slides...

# What's the point in a generative model for sounds?

#### **Theoretical Neuroscience**

- Understand neural receptive fields: if a latent variable model provides a computationally effective representation of sounds, neurons might encode p(latent|sound)
- **Psychophysics**: Play sounds to subjects (possibly drawn from the forward model), and compare their inferences with inference in the model.

#### **Machine Learning**

- Fill in missing data: e.g. to fill in an intermittent recording or remove artifacts
- Denoise sounds, Stream segregation, Compression

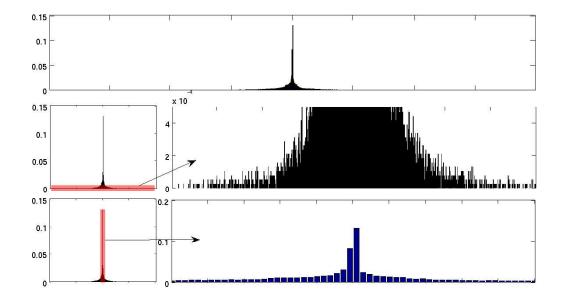
# Outline

- Natural auditory scene statistics Amplitude modulation is a key component
- Amplitude modulation in the auditory system a candidate organising principle (the auditory system is short on such things)
- Previous statistical models of natural scenes Gaussian Scale Mixture Models and AM
- A new model for sounds: The Gaussian Modulation Cascade Process
- On going issues...

# Natural Auditory Scene statistics: Acoustic ecology

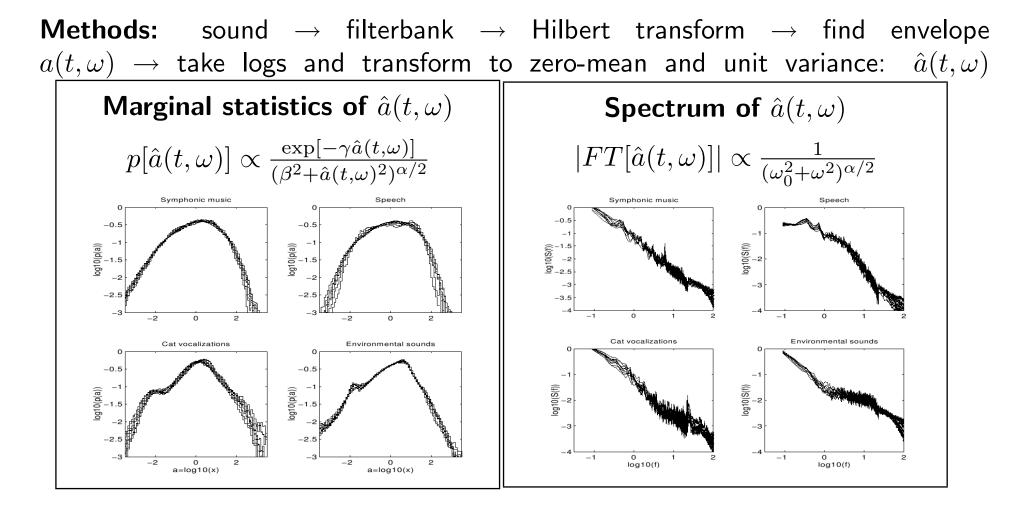
#### Marginal distribution

• very sparse (more so than in vision)



• WHY? Lots of soft sounds e.g. the pauses between utterances in speech sounds and rare highly structured localised events that carry substantial parts of the stimulus energy

# Statistics of Amplitude Modulation (Attias & Schreiner)



## **Results summary**

#### • Marginal distribution

- very sparse (finite prob of arb. soft sounds):
- Independent of filter centre frequency, filter bandwidth, time resolution.
- If AM stats were uncorrelated over time and frequency, CLT would predict increasing the filter bandwidth/time resolution would make the distribution more Gaussian.

#### • Spectrum of the amplitude modulations

- Independent of filter centre frequency
- Modified power law, indicating long temporal correlations (scale invariance)
- Independent of filter bandwidth (cf. Voss and Clarke 1/f)

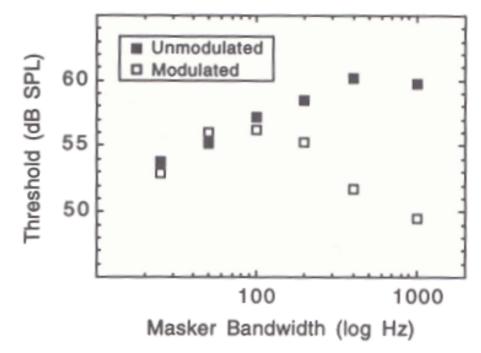
#### Implication: A good generative model of sounds should capture...

- 1. long correlations in AM across frequency bands and time (> 100ms)
- 2. Each location on the cochlea sees the same AM stats

# AM in the Auditory System - Highlights from lots of work

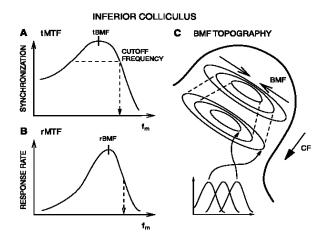
#### **Psychophysics: Comodulation masking release**

- task: detect a tone in noise.
- Alter the bandwidth of the noise and measure threshold
- Repeat but amplitude modulate the masker.



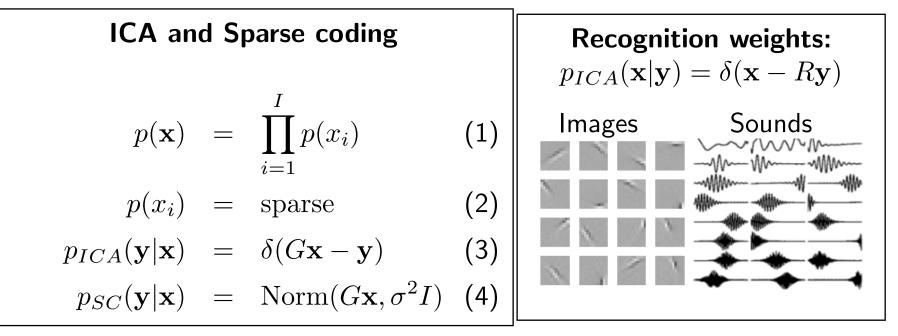
# **Electrophysiological data**

- Type 1 AN fibres phase lock to AM (implies temporal code), as we move up the neuraxis the tuning moves from temporal to rate.
- Evidence in IC for topographic AM tuning (Schreiner and Langer, 1988)



- Cortex: AM processing seems  $\sim$  filter independent (modulation filter bank?)
- Jury still out but AM may be a fundamental organising principle

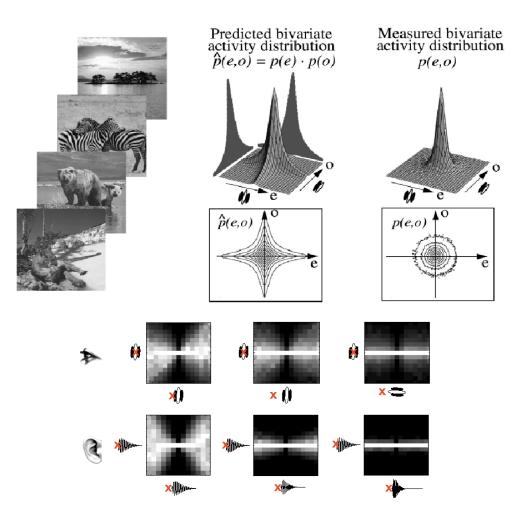
# What's wrong with statistical models for natural scenes?



**Problems:** 

- 1. Extracted latents are not independent: correlations in their power.
- 2. No explicit temporal dimension not a true generative model for sounds or movies

#### **1.** Empirical distribution of the latents - power correlations



# Explanation

- Caption for previous figure:
  - Expected joint distribution of latents was starry (top left).
  - Empirically the joint is found to be elliptical many more instances of two latents being high than expected (top right).
  - Another way of seeing this is to look at the conditionals (bottom): if one latent has high power then near by latents also tend to have high power.

#### • How do we improve the model?

- 1. Fix the bottom level  $p(\mathbf{y}|\mathbf{x}) = \delta(\mathbf{y} G\mathbf{x})$
- 2. Fixes recognition distribution  $p(\mathbf{x}|\mathbf{y}) = \delta(\mathbf{x} R\mathbf{y})$

3. 
$$p(\mathbf{x}) = \int d\mathbf{y} p(\mathbf{x}|\mathbf{y}) p(\mathbf{y}) \approx \frac{1}{N} \sum_{n} p(\mathbf{x}|\mathbf{y}_{n})$$

- 4. These are exactly the distributions plotted on the previous page
- 5. No matter what R is we get similar empirical distributions
- 6. So choose a new prior to match them ...

# Gaussian Scale Mixtures (GSMs)

- $\mathbf{x} = \lambda \mathbf{u}$ 
  - $\lambda \geq 0$  a scalar random variable
  - $\mathbf{u}\sim G(0,Q)$
  - $\lambda$  and  ${\bf u}$  are independent
- density of these *semi-parametric* models can be expressed as an integral:

$$p(\mathbf{x}) = \int p(\mathbf{x}|\lambda)p(\lambda)d\lambda = \int |2\pi\lambda^2 Q|^{-1/2} \exp\left(-\frac{\mathbf{x}^T Q^{-1} \mathbf{x}}{2\lambda^2}\right)p(\lambda)d\lambda$$
(5)

• e.g.  $p(\lambda)$  discrete  $\rightarrow$  MOG (components 0 mean),  $p(\lambda) =$ Gamma  $\rightarrow$  student-T.

Imagine generalising this to the temporal setting:

 $\mathbf{x}(t) = \lambda(t)\mathbf{u}(t) = \text{positive envelope} \times \text{carrier}$ Are we seeing the hall marks of AM in a non-temporal setting?

# Learning a neighbourhood (Karklin and Lewicki 2003, 05, 06)

- The statistical dependencies between filters depends on their separation (in space, scale, and orientation.)
- We'd like to learn these neighbourhoods of dependence
- Solution: Share multipliers in a linear fashion using a GSM with a generalised log-normal over the variances.

$$p(z_j) = \operatorname{Norm}(0, 1) \quad (6)$$
$$\lambda_i^2 = \exp\left[\sum_j h_{ij} z_j\right] \quad (7)$$
$$p(x_i | \mathbf{z}, B) = \operatorname{Norm}(0, \lambda_i) \quad (8)$$
$$p(\mathbf{y} | G, \mathbf{x}) = \operatorname{Norm}(G\mathbf{x}, \sigma^2 I) \quad (9)$$

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$\mathcal{Y}_{\mathcal{X}}^{(2)}$	W.	
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# A temporal GSMM: The proof of concept Bubbles model

$$p(z_{i,t}) = \text{sparse point process} \quad (10)$$
$$\lambda_{i,t}^2 = f\left[\sum_j h_{ij} \Phi(t) \otimes z_j(t)\right] \quad (11)$$
$$p(x_{i,t}|\lambda_{i,t}) = \text{Norm}(0, \lambda_{i,t}^2) \quad (12)$$
$$p(\mathbf{y}_t|G, \mathbf{x}_t) = \delta(G\mathbf{x}_t - \mathbf{y}_t) \quad (13)$$

- Temporal correlations between the multipliers are captured by the moving average  $\Phi(t) \otimes u_j(t)$  (creates a SLOW ENVELOPE)
- $\Rightarrow$  **Bubbles** of activity in latent space (both in space and time)
- Columns of  $h_{i,j}$  fixed and change smoothly to induce **topographic structure computationally useful**

# Learning

• Common to learn the parameters using zero-temperature EM:

$$q(X) = \delta(X - X_{MAP}) \approx p(X|Y)$$
(14)

- uncertainty and correlational information is lost.
  - 1. Effects learning
  - 2. To compare to neural data need to specify a mapping:  $p(\text{spike trains } | \mathbf{y}) = f[q(\mathbf{x} | \mathbf{y})] = f(X_{MAP})$  for this approximation.
  - 3. BUT we believe neural populations will **represent uncertainty and correlations** in latent variables.

We'd like to retain variance and correlational information, both for learning and for comparison to biology.

## Motivations for the GMCP

- 1. Sparse outputs.
- 2. Explicit temporal dimension, smooth latent variables.
- 3. **Hierarchical prior** that captures the AM statistics of sounds at different time scales: cascade of modulatory processes, with slowly varying processes at the top modulating more rapidly varying signals towards the bottom.
- 4. Learnable; and we would like to preserve information about the uncertainty, and possibly correlations, in our inferences.

### The Gaussian Modulation Cascade Process

# Dynamics:

$$p(x_{k,t}^{(m)}|x_{k,t-1:t-\tau_m}^{(m)},\lambda_{k,1:\tau_m}^m,\sigma_{m,k}^2) = \operatorname{Norm}\left(\sum_{t'=1}^{\tau_m}\lambda_{k,t'}^{(m)}x_{k,t-t'}^{(m)},\sigma_{m,k}^2\right)$$

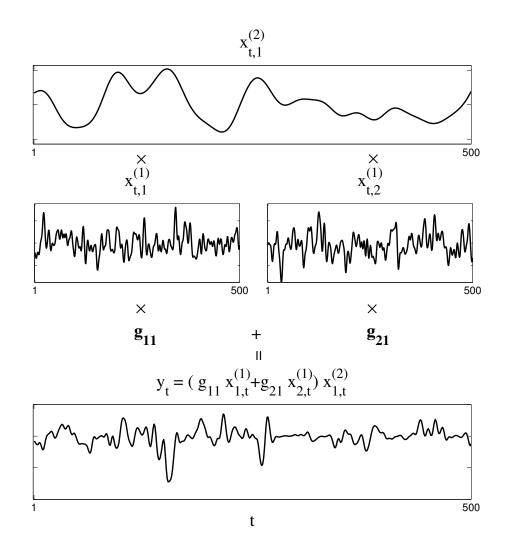
### Emission Distribution:

$$p(\mathbf{y}_t | \mathbf{x}_t^{(1:M)}, \mathbf{g}_{k_1:k_M}, \sigma_y^2) = \operatorname{Norm}\left(\sum_{k_1:k_M} \mathbf{g}_{k_1:k_M} \prod_{m=1}^M x_{k_m,t}^{(m)}, \sigma_y^2 I\right)$$

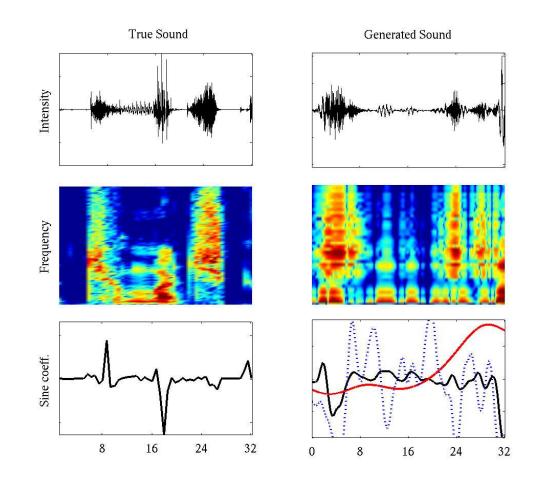
# Time-frequency representation:

 $\mathbf{y}_t = \mathsf{filter} \mathsf{ bank} \mathsf{ outputs}$ 

**e.g.**  $M = 2, K_1 = 2, K_2 = 1, D = 1$ 



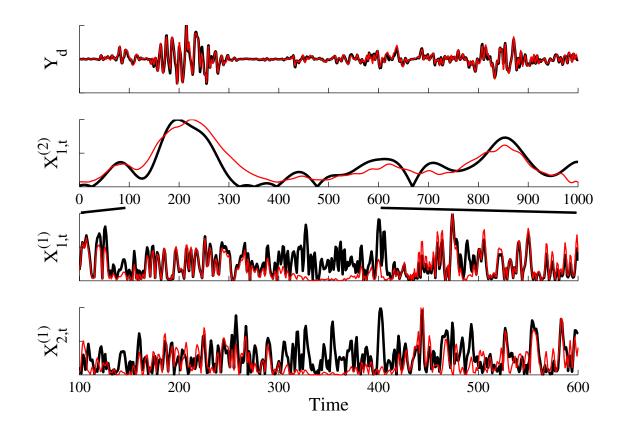
e.g. 
$$M = 4, K_1 = 4, K_2 = 2, K_3 = 2, K_4 = 1, D = 80$$



#### **Comments on the model**

- A GSM: latent = rectified Gaussian  $\times$  Gaussian
- Emission distribution related to Grimes & Rao, Tenenbaum & Freeman (for M=2) and Vasilescu & Terzopoulos for general M., but the temporal priors allow us to be fully unsupervised.
- As  $p(x_{1:K,1:T}^m | x_{1:K,1:T}^{1:M \neq m}, \mathbf{y}_{1:T}, \theta)$  is Gaussian, there are a family of variational EM algorithms we can use to learn the model.

### **Inference and Learning: Proof of concept**



### Future directions and current issues

### DIRECTIONS

- correlated prior: speech is usually periodic (voiced) or unvoiced mutually exclusive, easier to represent sweeps.
- **non-local features**: make G temporal to capture sweeps

### ISSUES

- **Representation**: real sounds live on a hyper-plane in filter-bank space can we project our model onto this manifold?
- Initialisation: The free energy has lots of local minima: use Slow modulations analysis to initialise  $\arg\min_{\mathbf{g}_n} \left\langle \left[ \frac{da(\mathbf{g}_n^T \mathbf{y})}{dt} \right]^2 \right\rangle$  such that  $\langle a(\mathbf{g}_n^T \mathbf{y}) a(\mathbf{g}_m^T \mathbf{y}) \rangle = \delta_{mn}$
- How do we map posteriors to spike-trains:  $p(\text{spike trains } | \mathbf{y}) = f[Q(\mathbf{x} | \mathbf{y})]$ ?

Model	$\mathbf{p}(\mathbf{x}^{(1)})$	$\mathbf{p}(\mathbf{y} \mathbf{x}^{(1)})$
ICA	sparse	$\delta(y - Gx^{(1)})$
SC	sparse	$\operatorname{Norm}(Gx^{(1)}, \sigma_y^2 I)$

Assumption: Latent variables are sparse.

Model	$\mathbf{p}(\mathbf{x}^{(2)})$	$\mathbf{p}(\mathbf{x}^{(1)} \mathbf{x}^{(2)})$	$\mathbf{p}(\mathbf{y} \mathbf{x}^{(1)})$
ICA	N/A	sparse	$\delta(y - Gx^{(1)})$
SC	N/A	sparse	Norm $(Gx^{(1)}, \sigma_y^2 I)$
GSM	$\operatorname{Norm}(0,I)$	$\operatorname{Norm}(0,\lambda_i^2)$	$\operatorname{Norm}(Gx^{(1)}, \sigma_y^2 I)$
		$\lambda_i^2 = \exp(h_i^T x^{(2)})$	

Assumption: Latents are sparse, and share power.

•  $\mathbf{x}^{(1)} = \lambda \mathbf{u}$ 

–  $\lambda \geq 0$  a positive scalar random variable,  $\mathbf{u} \sim G(0,Q)$ 

Model	$\mathbf{p}(\mathbf{x}^{(2)})$	$\mathbf{p}(\mathbf{x^{(1)}} \mathbf{x^{(2)}})$	$\mathbf{p}(\mathbf{y} \mathbf{x}^{(1)})$
ICA	N/A	sparse	$\delta(y - Gx^{(1)})$
SC	N/A	sparse	$Norm(Gx^{(1)}, \sigma_y^2 I)$
GSM	$\operatorname{Norm}(0, I)$	$\operatorname{Norm}(0,\lambda_i^2)$	$Norm(Gx^{(1)}, \sigma_y^2 I)$
_		$\lambda_i^2 = \exp(h_i^T x^{(2)})$	
SFA	N/A	$\operatorname{Norm}(\gamma x_{t-1}, \sigma^2)$	$\delta(y - Gx^{(1)})$

Assumption: Latents are slow.

Model	$\mathbf{p}(\mathbf{x}^{(2)})$	$\mathbf{p}(\mathbf{x^{(1)}} \mathbf{x^{(2)}})$	$\mathbf{p}(\mathbf{y} \mathbf{x}^{(1)})$
ICA	N/A	sparse	$\delta(y - Gx^{(1)})$
SC	N/A	sparse	Norm $(Gx^{(1)}, \sigma_y^2 I)$
GSM	$\operatorname{Norm}(0, I)$	Norm $(0, \lambda_i^2)$	$Norm(Gx^{(1)}, \sigma_y^2 I)$
		$\lambda_i^2 = \exp(h_i^T x^{(2)})$	
SFA	N/A	Norm $(\gamma x_{t-1}, \sigma^2)$	$\delta(y - Gx^{(1)})$
Bubbles	point-process	$\operatorname{Norm}(0,\lambda_{i,t}^2)$	$\delta(y - Gx^{(1)})$
		$\lambda_{i,t}^2 = f(h_i^T x_t^{(2)} \otimes \phi_t)$	

Assumption: Latents are sparse, slow (and share power).