

Introduction

• Framework for (polyphonic) audio — linear signal model for magnitude spectrum $x_t(k)$:

$$\hat{x}_t(k) = \sum_{n=1}^N g_{n,t} b_n(k)$$

- $g_{n,t}$ is the gain of basis function n in frame t, and $b_n(k)$, $n = 1, \ldots, N$ are the basis functions
- Spectrogram modeled as a sum of components, each of which has a fixed magnitude spectrum and time-varying gain
- Applied e.g. in sound source separation: each sound represented with distinct basis functions
- Unsupervised learning estimation algorithms: ICA [1], NMF [3], sparse $\operatorname{coding}\left[4\right]$
- Supervised learning: NMF, sparse coding, vector quantization
- Distinct bases required for each pitch/phoneme-combination makes the estimation and clustering less reliable

Proposed Source-Filter Model

- Each basis $b_n(k)$ is described as a product of the magnitude spectra of an excitation (source) $e_i(k)$ and a filter $h_j(k)$.
- "Source" refers to a vibrating object such as a guitar string varies with pitch
- "Filter" represents the resonance structure of the rest of the instrument which colors the produced sound — varies with timbre
- Model for the magnitude spectrum of mixture signal:

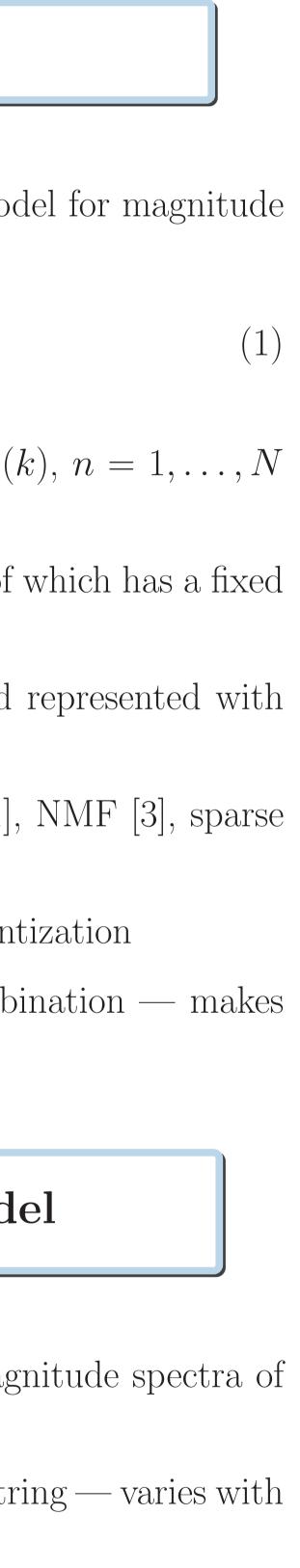
$$\hat{x}_t(k) = \sum_{i,j} g_{i,j,t} e_i(k) h_j(k)$$

- Smaller number of parameters bases are restricted to $b_n(k) =$ $e_i(k)h_j(k)$
- The model associates components with the same timbre (resp. pitch), leading to an automatic clustering of bases to sound sources (resp. musical notes).

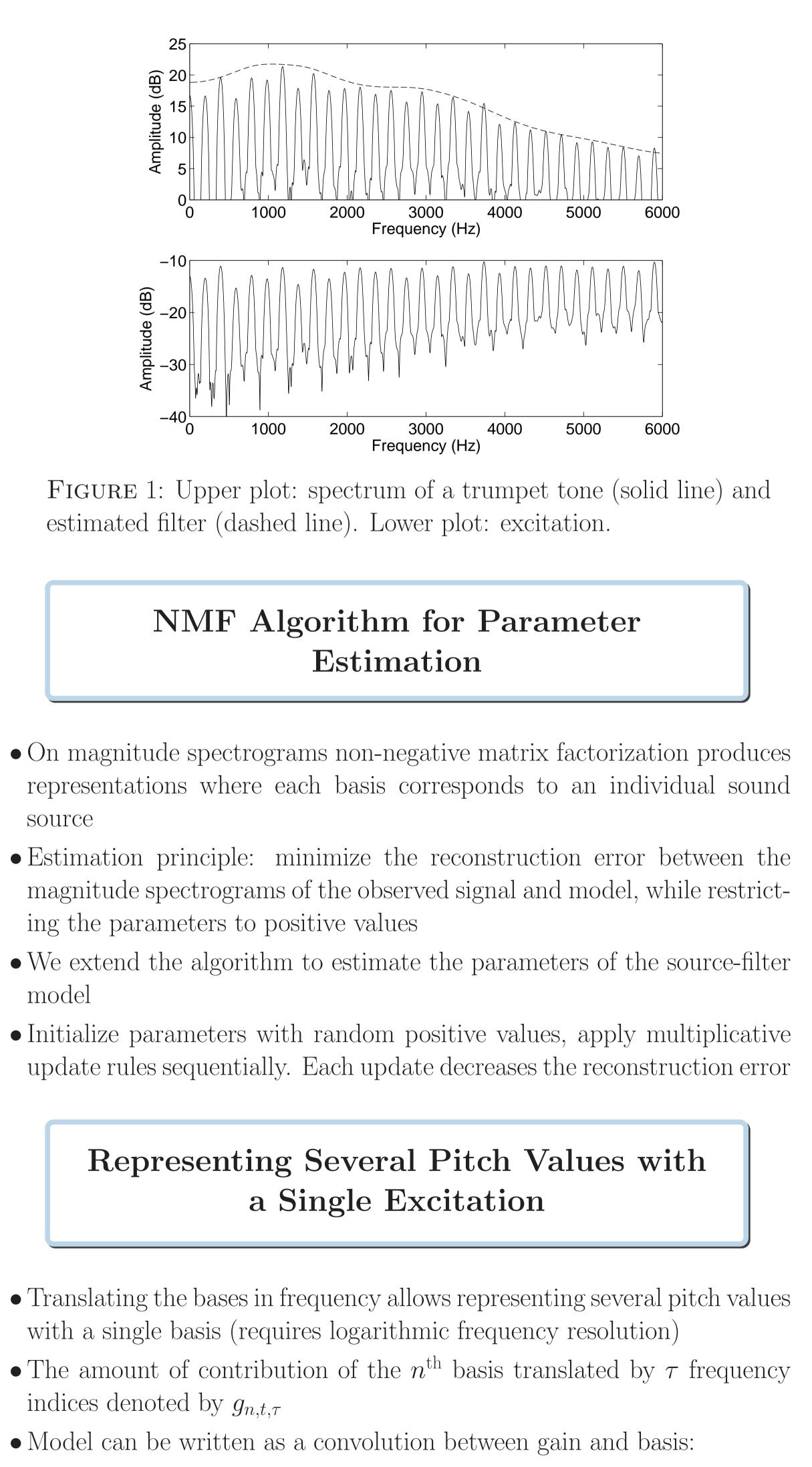
Analysis of Polyphonic Audio Using Source-Filter Model and **Non-Negative Matrix Factorization**

Tuomas Virtanen and Anssi Klapuri

tuomas.virtanen@tut.fi, anssi.klapuri@tut.fi Institute of Signal Processing, Tampere University of Technology, Tampere, Finland



(2)



- source
- ing the parameters to positive values
- model

- indices denoted by $g_{n,t,\tau}$

$$\hat{x}_t(k) = \sum_{n,\tau} g_{n,t,\tau} b_n(k)$$

 $(k-\tau)$

(3)

ald [2] and Virtanen [5, pp. 57-65]

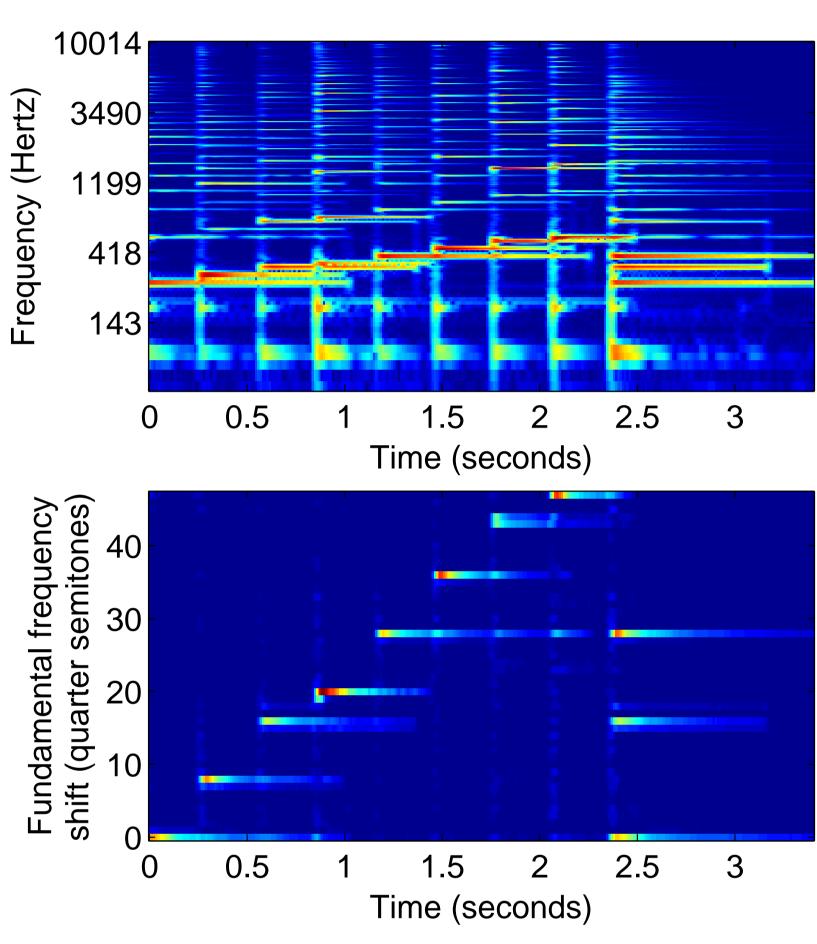


FIGURE 2: Representing several fundamental frequency values with a single basis.

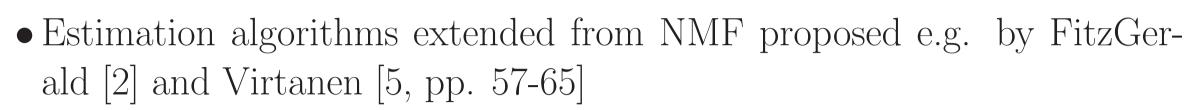
- the filter becomes translated

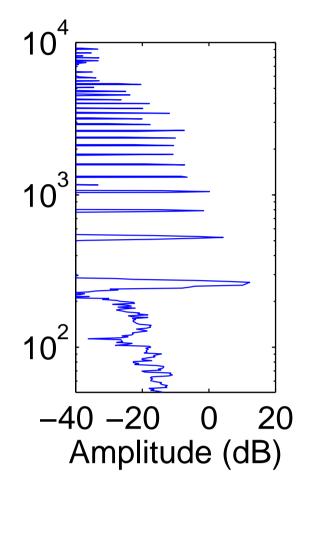
$$\hat{x}_t(k) = \sum_{i,j,\tau} g_i$$

• Estimation algorithm extended from NMF

References

- International Computer Music Conference, Berlin, Germany, 2000.
- Spain, 2005.
- 2003.
- 2006. Accepted for publication.
- versity of Technology, 2006. available at http://www.cs.tut.fi/~tuomasv.





(4)

• Drawback: the translation affects the entire basis function, and therefore

• Proposed model: different fundamental frequency values obtained by translating a single harmonic excitation while keeping the filter fixed

 $g_{i,j,t,\tau}e_i(k-\tau)h_j(k).$

^[1] M. A. Casey and A. Westner. Separation of mixed audio sources by independent subspace analysis. In

^[2] Derry FitzGerald, Matt Cranitch, and Eugene Coyle. Generalised prior subspace analysis for polyphonic pitch transcription. In Proceedings of International Conference on Digital Audio Effects, Madrid,

^[3] Paris Smaragdis and J. C. Brown. Non-negative matrix factorization for polyphonic music transcription. In IEEE Workshop on Applications of Signal Processing to Audio and Acoustics, New Paltz, USA,

^[4] Tuomas Virtanen. Monaural sound source separation by non-negative matrix factorization with temporal continuity and sparseness criteria. IEEE Transactions on Audio, Speech, and Language Processing,

^[5] Tuomas Virtanen. Sound Source Separation in Monaural Music Signals. PhD thesis, Tampere Uni-